

### SR# 4321 STS-129 (ULF3) Baselined Flight Manifest October 9, 2008 PRCB

MO3/Michael Darnell Mission Integration Manager





STS-129 (ULF3) Baselined Flight Manifest

Presenter MO3/Michael Darnell Date Page 2 **Oct. 2008** 

# **Agenda**

- Purpose of SR#4321
- **FDRD Flight Manifest**
- STS-129 Cargo Bay Arrangement Drawing
- Ascent Performance/Flight Design
- **Documentation Status**
- ISS-ULF 3 Mission Manifest
  - ELC 1, ELC 2, MISSE 7A, MISSE 7B, SASA, ISS Middeck (powered payloads)
- Mission Objectives
- Backup Charts
  - Preliminary Overview Timeline with EVA 1 on FD4
  - Preliminary Overview Timeline with EVA 1 on FD5
  - ISS Cargo Element Manifest Overview
  - Personnel Assignments





Purpose of SR 4321

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# Purpose:

Informational presentation to the PRCB on the mission content and orbiter configuration required for the STS-129 / ISS-ULF3 mission.

- CR# S072129, to baseline STS-129 into the FDRD and initiate the flight production process was reviewed by the FOICB on 9/22/08 with recommendation for OSB approval due to PRCB schedule conflicts.
- Flight Production process in place to support a target launch date of October 15, 2009.





STS-129 (ULF3) Baselined Flight Manifest

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This CR Request is to: Add a column in NSTS 07700 Volume III FDRD, Table 4.1 as follows:

ΑCTIVITY	STS-129	P/L MANIFEST	
TARGET LAUNCH DATE CONFIGURATION	10-15-09	-PAYLOAD BAY	ISS ULF 3 (ELC1, ELC 2, MISSE 7A, MISSE 7B, SASA)
-ORB (FLT NO) -ET	OV-103 (37) ET-133	-MIDDECK	ISS ULF 3, MAUI <sup>(a)</sup> , SEITE <sup>(a)</sup> , SIMPLEX <sup>(a)</sup>
-SRB'S	BI-140	OPERATIONS	
-SSME SETTING -POSITION 1	RSRM-108 104.5/104.5%	-PAD/MLP -INCLINATION -INSERTION ALT	A/TBD 51.6 DEG
-POSITION 2	TBD TBD	-MECO TGT	122 NM DIR INSERTION
-SOFTWARE REL	TBD OI-34	-FLT DURATION	ZARAGOZA 15 + 1 DAYS
-GN2 TANKS	5 6		4+ 1 6 Up / 7 Down <sup>(b)</sup>
	SRMS, OBSS, ODS, SSPTS		KSC
		INSTRUMENTATION	Rescue Flight for STS-128
		REMARKS	<sup>(b)</sup> One Crew Return











### STS-129 Flight Design and APM

**Ops Hi Q** 

5 Full

6 Full

Block II

4 + 1

854 lbs total

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### Flight Design:

**Ref. SPICE Baselined Data** Package 9/10/08

Ascent performance margin (APM): 1198 lbp

- **Ascent Design** •
- **Cryo Tanks:** •
- Forward RCS: 1912 lbs/offload •
- **GN2** Tanks:
- Water •
- Ballast aft: •
- SSME's: •
- EVAs: •
- **Rendezvous Altitude** ٠
- ELC 1: •
- **ELC 2:** •

•

- SASA w/FSE/SPA Beam •
- MISSE 7A PEC w/ICAPC •
- **MISSE 7B PEC w/ICAPC** 
  - Middeck: 8,600 lbs (969 lbs ISSP mission unique items)

Standard offload (180 lbs)

195 nmi

600 lbs

216 lbs

216 lbs

14,100 lbs

13,527 lbs





STS-129 Flight Design and APM (Cont'd)

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- Downweights and X-cg: C.G.'s within limits for all Abort cases and NEOM.
  - NEOM 205,768 @ 1081.5 in cg (Cg Limit: 1075.2 to 1109.0 in.)
  - RTLS 241,557 @ 1079.8 in cg (Cg Limit: 1076.7 to 1109.0 in.)
  - TAL 239,485 @ 1080.9 in cg (Cg Limit: 1076.7 to 1109.0 in.)
  - AOA 233,271 @ 1075.7 in cg (Cg Limit: 1075.2 to 1109.0 in.)
  - NO DOCK PLS BLST 233,124 @ 1075.7 in cg (Cg Limit: 1075.2 to 1109.0 in.)
  - Worst Case FWD CG (217,276 @ 1071.6 in cg) results if the ELC-2 pallet (aft payload bay installed pallet) is deployed first.
    - To protect for this ops scenario would require additional orbiter lead ballast (~2,000 lbs) and a decrease in ISS upmass carrying capability (2-3 ORUs).
    - This worst case configuration scenario can be precluded if the ELC-1 pallet is deployed first.
      - Requires a mission operational crew timeline constraint to remove ELC-1 first
      - Mission operational constraint approved by both the FOICB (7/9/07) and JMICB (7/11/07).
    - Successful deployment of ELC-1 first protects for forward cg margin and provides acceptable X-cg for an anytime de-orbit.







**ISS ULF 3 Manifest** SR #4321

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### **ISS ULF 3 Mission Manifest\*:**

- ELC1 (Battery Charge/Discharge Unit (BCDU), Plasma Contactor Unit (PCU), Latching End Effector (LEE), Control Moment Gyro (CMG), Nitrogen Tank Assembly (NTA), Ammonia Tank Assembly (ATA), Pump Module (PM), 2 empty P/L Passive Flight **Releasable Attachment Mechanism (PFRAM))**
- ELC2 (High Pressure Gas Tank (HPGT), Cargo Transport Container (CTC), Control Moment Gyro (CMG), Pump Module (PM), NTA, Mobile Transporter/Trailing Umbilical System (MT/TUS), Materials on International Space Station Experiment (MISSE)-7 Flight Support Equipment (FSE), 1 empty PFRAM, & 1 empty P/L PFRAM)\*
- 3 Sidewalls (SASA, MISSE-7A PEC, MISSE-7B PEC)\*
- Shuttle Integration H/W

\*As documented in Mission Integrated Manifest (MIM) Rev J, approved 6/20/08

### Materials on International Space Station Experiment (MISSE)

Utilization:

MISSE-7A & 7B Passive Experiment Containers (PECs)

Payload in development

Date

**Sidewall Carriers:** 

**Pre-Positioned Spare:** 

S-Band Antenna Sub-Assembly (SASA)

**Repaired from 10A return** 

### **Middeck Payloads:**

**1** Powered Payload

• General Laboratory Active Cryogenic ISS Equipment Refrigerator (GLACIER) (2 MLE) – Rear Breather





STS-129 Mission Objectives

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### **Mission Objectives**

- Return one ISS crewmember (Expedition 20 Flight Engineer 4)
- Deliver and install 2 ELCs with pre-positioned spares and utilization
- Deliver MISSE-7 PECs and install to ELC2
- Deliver spare SASA and transfer to stowage location on Z1
- Remove spare HPGT from ELC2 and install to ISS Airlock





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**Backup Charts** 





Preliminary STS-129 (ULF3) Timeline EVA 1 on FD4

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Date

# STS-129/ULF3 Overview Timeline (15+1+2)

Last Updated: 25August2008 00/0 2 3 MET .1 4 5 8 9 10 11 12 6 7 P/T2 RMS Post Sol STS ASC 01 C/O Insert Setup ш Orb Att -ZLV +YV -ZLV -XVV MET 12 13 14 15 16 17 18 19 20 21 22 23 01/0 1 2 3 4 5 6 7 8 9 10 11 RNDZ 02 **OBSS Survey (STBD &** Port Survey & OBSS NC2 NC3 STS Meal Tools Nose), EMU Checkout Berth c/o ш Orb Att -ZLV -XVV Survey (Inertial) -ZLV -XVV MET 12 13 14 15 16 17 18 19 20 21 22 23 02/0 1 2 3 4 5 6 7 8 9 10 11 EVA 1 STS RNDZ Campout EVA Prep & Hello Hatch Proc 8 DOCK ISS D Meal Open Transfer D Rvw Ë RNDZ LVLH TEA -ZLV -XVV -ZLV +YVV Orb Att WS/PDGF WS4/Node2 ^ Water Dump 12 13 14 15 16 17 18 19 20 21 22 23 03/0 2 3 4 5 6 7 8 9 10 11 MET 1 Post EVA STS EVA 1 (SASA Transfer from PLB SWC - Z1) 4 Campout EVA Prep w/H2O, ISS SSRMS/SRMS Support Metox Δ Orb Att LVLH TEA Ū. WS7/PDGF4 WS/PDGF WS4/Node2 MET 12 13 14 15 16 17 18 19 20 21 22 23 04/0 1 2 3 4 5 6 7 8 9 10 11 EVA 2 STS Install ELC1 to P3 Lwr CAS EVA 2 Prep Campout SSRMS w/ 02 Proc Meal to PDGF1 ISS D Transfer Transfer D Rvw Orb Att LVLH TEA LL. WS/PDGF WS7/PDGF4 WS2/PDGF1 ^ N2 Transfer Init





Preliminary STS-129 (ULF3) Timeline EVA 1 on FD4 (Cont'd)

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•	WS/PDGF											W	S2/PDG	F1		T	·							
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Preliminary STS-129 (ULF3) Timeline EVA 1 on FD4 (Cont'd)

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Preliminary STS-129 (ULF3) Timeline EVA 1 on FD4 (Cont'd)

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	MET 1	2 1	3 1	4 15 1	16 17	18 1	9 20	21	22	23	15/0	1	2	3 4	I.	5	6	7	8	9	10	11
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#### Assumptions:

- Timeline layout doesn't assume actual mission trajectory.

- Robotic support during EVA 4 is still TBD.





Overview Timelime (15+1+2) EVA 1 on FD5

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Last Updated: 23September2008

# STS-129/ULF3 Overview Timeline (15+1+2) EVA1 on FD5

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Overview Timelime (15+1+2) (Cont'd) EVA1 on FD5

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#### Assumptions:

- Timeline layout doesn't assume actual mission trajectory.

- Robotic support during EVA 4 is still TBD.

- All robotic activities and WS/PDGF positions are under review. Activities may change based on review.





ISS ULF 3 Manifest SR 4321





ULF3 – Oct 2009



General Laboratory Active Cryogenic ISS Equipment Refrigerator (GLACIER)





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Date





SASA



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SASA is an assembly that includes the S-band RF Group (RFG) and a standard support structure. The S–band RF Group (RFG) consists of three units: a Transmit/Receive Amplifier (TRA), a High Gain Antenna (HGA) and a Low Gain Antenna (LGA). The TRA contains the transmit and receive sections. power supplies and an antenna controller. The HGA is a horn and gimbal assembly mounted on a pedestal. The LGA is a fixed omnidirectional antenna. The TRA serves as a structural platform for the antennas. The support structure consists of a mast, a mounting surface for the RFG and a baseplate fitting. The baseplate fitting is the structural interface between the SASA and the primary structure. The support structure routes and supports a single harness terminating in three connectors at the connector panel for operational and heater power, command and status signals and RF transmit and receive signals.

Photo from 5A





### **MISSE PEC Sidewall**

Presenter MO3/Michael Darnell
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The Materials International Space Station Experiment-7 (MISSE-7) is a test bed for materials and coatings attached to the outside of the International Space Station (ISS) being evaluated for the effects of atomic oxygen, ultraviolet, direct sunlight, radiation, and extremes of heat and cold. This experiment allows the development and testing of new materials to better withstand the rigors of space environments. Results will provide a better understanding of the durability of various materials when they are exposed to the space environment with applications in the design of future spacecraft. (MISSE-6 shown)

Photo of MISSE-6 from 1JA





# **Robotics Tasks**



### Activity:

- ELC1 installation to P3 Lower (UCCAS #2)
  - SRMS unberth carrier from PLB and handoff to SSRMS
- ELC2 installation to S3 Upper Outboard (PAS #1)
  - SRMS unberth carrier from PLB and handoff to SSRMS
- <u>Note</u>: Order of carrier deployment depends which ELC is manifested forward in the PLB. The ULF3 ballast scenario requires that the forward ELC be deployed first.







# Robotics Tasks, cont'd

Date

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Rationale for Designated CAS Sites: A preferred attach site exists for each ELC based its ORU/Payload complement Desire to place spare ORUs in close proximity to future R&R locations • Desire that certain ORUs be evenly distributed between port and starboard sides of ISS (i.e., NTA, ATA, Pump Module on both P1 & S1) · Payload viewing requirements (zenith vs. nadir) ELC2 **Keel Side** ESP-3 Keel Side ELC1





# **ULF-3 ELC 1 Configuration**

Presenter MO3/Michael Darnell Date Page 26 Oct. 2008

**Bottom** 

Тор



### **Pre-Positioned Spares:**

- 1 Battery Charge/Discharge Unit (BCDU)
- 1 Control Moment Gyro (CMG)
- 1 Nitrogen Tank Assembly (NTA)
- 1 Pump Module (PM)
- 1 Ammonia Tank Assembly (ATA)
- 1 Plasma Contactor Unit (PCU)
- 1 Latching End Effector (LEE)

### Utilization:

2 empty P/L PFRAMs for future payload use Note: Keel remains in Orbiter upon ELC deployment











### **Battery Charge/Discarge Unit (BCDU)**

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- Serves a dual function of charging the batteries during insolation periods, and providing conditioned battery power to the primary power buses during eclipse periods
- BCDU initial start-up includes activation of the DC/DC power converter, Local Data Interface (LDI), and control and monitoring circuitry
- Includes provisions for battery status monitoring and protection from power circuit faults
- Commanded and monitored by a 1553 data bus.







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The Pump Module (PM) is the primary ETCS heat transportation component. There are two PM ORUs, one located on the S1 (Loop A) Truss and the other on the P1 (Loop B) Truss. The Pump Module ORU circulates liquid ammonia at a constant flowrate to a network of coldplates and heat exchangers located on the external trusses and USOS modules, respectively. The major components in the PM include a Pump and Control Valve Package (PCVP), an accumulator, isolation and relief valves, and various temperature, flow, and pressure sensors.





# AMMONIA TANK ASSEMBLY (ATA)

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The primary function of the ATA is to store the ammonia used by the ETCS. The major components in the ATA include two ammonia storage tanks, isolation valves, heaters, and various temperature, pressure, and quantity sensors. Each ATA will be used to fill their respective ETCS loop on startup (loops are launched with nitrogen in the lines) and to supply makeup fluid to that loop. It also assists the PM accumulator with ammonia inventory management, and provides the capability to vent the PM and ATA by connection to an external nonpropulsive vent panel. If required, it can be used to replenish the PVTCS fluid lines.





# NITROGEN TANK Assembly (NTA)

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The primary function of the NTA is to store the high pressure nitrogen that is used to control the pressurization of the ammonia tanks in the ATA. The NTA mounts to the S1 (Loop A) and P1 (Loop B) truss segments and is connected to the ATA by selfsealing ODs. The major components in the NTA include a nitrogen tank, a Gas Pressure **Regulator Valve (GPRV), isolation** and vent valves, heaters, and various temperature and pressure sensors. The GPRV provides pressure control as well as highpressure nitrogen isolation and overpressure protection of downstream components.





# Plasma Contactor Unit (PCU)

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Power Electronics Unit (PEU)



Gas Feed System (GFS)

The Plasma Contactor Unit ORU is an integral element of the Station grounding design. Two PCUs are mounted on the Z1 truss. Used to keep the electrical potential between the surrounding space plasma and the station structure from reaching damaging potentials (maintain ±40 Vdc). To minimize this potential difference, Plasma Contactor Units (PCUs) located on the Z1 truss (one operational and one backup) generate plasma from xenon gas and emit a stream of electrons into space. This electron emission results in a "grounding-strap" that effectively grounds the ISS to the space environment, minimizing the potential difference as well as related hazards to the ISS and crew.

Composed of 3 subsystems: GFS: Gas Feed System HCA: Hollow Cathode Assembly PEU: Power Electronic Unit





# Space Station Remote Manipulator System – Latching End Effector (SSRMS LEE)

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The Space Station Remote Manipulator System (SSRMS) is equipped with two Latching End Effectors (LEEs). Either LEE can be used as the arm's base, while the other is used to grasp payloads or new base locations. To grasp a Grapple Fixture (GF), the arm is first maneuvered to position the tip of the LEE over the Grapple Fixture (GF). A series of mechanisms is then actuated to rigidly attach the LEE to the GF. The LEE grapples PDGFs to act as a base or to provide connectivity to powered payloads or the **Special Purpose Dexterous Manipulator** (SPDM). PDGFs are equipped with electrical connections for the arm and an interface to which the LEE can be latched. The LEE is composed of the following components:

• Snare Mechanism - (Three cables each connecting two rings that rotate with respect to each other.)

• Snare Rings - (rings are mounted on a retractable carriage)

• Snare Motor Module (SMM) - (Rotates rings causing the cables to close like the iris of a camera, wrapping around a shaft on the GF).











# **Control Moment Gyroscope (CMG)**

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The CMG is a gyroscopic device consisting of a motor-driven constant-speed momentum wheel mounted in gimbals that provide two degrees of freedom for the rotor spin axis. The constant-speed wheel is held in an inner gimbal, which is coupled, to an outer gimbal through a pivot, perpendicular to the wheel spin axis. The outer gimbal, in turn, is coupled to the base through a pivot, perpendicular to the inner gimbal axis. Each gimbal pivot contains a geared torquer and a resolver used together for momentum vector control and management. This momentum exchange device is used to apply reaction torque to the Space Station for attitude control.

Photo from 13A.1





### Mobil Transporter/Trailing Umbilical System (MT/TUS)

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Photo from STS-121 / ULF1.1

The MT IMCAs receive power and communication via the TUS. Any MSS equipment attached to the MT also transmits and receives communication via the TUS. The TUS is analogous to an extension cord for the MT. It comprises a Reel assembly and the TUS cable itself. There are two TUSs for the MT, one on the zenith side of the MT and one on the nadir side of the MT. The TUS reels are located on the S0 truss and have the capability to extend and retract the TUS cable as required by MT translations. The TUS operates via the use of a swing arm. As the TUS cable becomes slack, the swing arm lowers. Once the arm has lowered far enough, magnetic switches on the arm trip and the IMCA is commanded to retract the cable. The cable is retracted until the swingarm returns to its nominal position. As the TUS cable becomes taught, the swingarm raises and the IMCA is commanded to extend to TUS cable.





STS-129/ULF 3 Personnel Assignments

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•Flight Mgr:	Mary Anne Plaza
•ISS LPM:	Hubert Brasseaux
•MIM:	Michael Darnell
•EVA Project	Marc Ciupitu
•SSP Flight Director:	Michael Sarafin
<ul> <li>ISS Flight Director:</li> </ul>	Brian Smith
•Lead ACO:	Robert Napp
•Lead FAO:	Telisha Harris
•USA Flight Mgr:	Robert Reynolds
•Flight Design Mgr:	Jared Renshaw
•Training Mgr:	Stephanie Turner
•USA/Cargo Mission Manager:	Yvette Carmona
•Crew Compartment Engineer:	Tracy Hunt
•MOD/USA Flt Prod. Manager:	Linda K. Grubbs
•KSC/Orbiter Manager:	Joe Deen
•KSC/Shuttle Payload Proj. Mgr:	Debbie Hahn
•CDR	Charlie Hobaugh